## 743CB Series FIELD STATION MICRO Controller

The 743CB is a self-contained, field-mounted, microprocessor-based controller with the ability to perform control functions for up to two independent loops. In addition to the standard proportional, integral, and derivative (PID) functions, the controller provides many enhanced functions including Foxboro's patented EXACT tuning algorithm, userconfigurable control functions, auto selector control, split range outputs, auto/manual transfer stations, assignable 3 -variable indicator functions, totalization, a comprehensive calculation capability, and signal conditioning. Standard controller signals include: four analog inputs, two frequency inputs, two contact inputs, an optional platinum RTD direct input, two analog outputs, and two contact outputs.
A fluorescent display is used to show the control variables in bargraph format, and to provide precision digital readout. It also displays an electronic loop tag, controller status, and alarm indication. A keypad, located on the front of the controller, is used for operator interface and configuration.
The controller is housed in a field-mounted enclosure that meets IEC IP66 and that also provides the environmental and corrosion resistant protection of NEMA Type 4X. The enclosure can be mounted to a surface or panel, or mounted to a nominal DN50 or 2 in pipe.

## FEATURES

- Two Independent PID Controllers
- Single Station Cascade Control
- Single Station Auto Selector Control
- Split Range Outputs
- Ratio Control
- Batch (Discontinuous) Control
- Totalization
- 3-Variable Indicators
- Auto/Manual Transfer Stations
- Assignable Alarms
- Algebraic Computation
- Dynamic Compensation with Lead/Lag, Impulse, and Dead Time Functions

- Boolean Logic Capability
- EXACT Control (Foxboro U.S. Patent RE 33267)
- Flexible Configuration Blocks with Internal Signal Routing
- Fully Interactive Display
- Configuration and Display of an Independent Variable
- Pulse Driven Input
- RS-485 Serial Communications for Operation and Configuration
- Nonvolatile Memory
- Transportable Configuration
- Power Failure Recovery Logic
- Front Panel Keypad for Both Configuration and Operator Interface
- Internal Signal Sources for Calibration
- Integral Field Power Supply
- Passcode Security

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## TWO INDEPENDENT CONTROLLERS

Two completely independent control strategies can be used. All control support functions are available for both loops, thereby allowing high-performance, enhanced control of each loop.

## CASCADE CONTROL

With this controller configuration, the output of one of the controllers (primary controller) drives the set point of the other (secondary) controller. This configuration can improve the performance of certain control loops where load disturbances are a factor.

## AUTO SELECTOR CONTROL

Two controllers with a single selected output are combined in this configuration to provide constraint control or dual mode control. The choice of lower, higher, or logic-selected output is configurable. The inherent design prevents controller windup and offers independent or interlocked auto/manual functions.

## SPLIT RANGE OUTPUTS

The two 4-20 mA outputs can be driven from a single controller. This allows one measured variable to be controlled by two manipulated variables. A typical application is a temperature control system in which both the heating medium and the cooling medium are manipulated.

## ACTUAL OUTPUT INDICATION

The output bargraph and digital indicator can be configured to display the actual 4-20 mA output value, or any analog signal, such as valve position feedback.

## TOTALIZERS

Up to two 7-digit totalizers are available. The totalizers can be set to integrate up to a preset value or down from a preset value, and produce a logic event output. Any internal or external signal can be totalized.
Totalization and EXACT tuning are mutually exclusive. For example, if one controller is configured for EXACT tuning, only one totalizer is available.

## EXACT CONTROL

EXACT control uses microprocessor technology to make ongoing controller adjustments based on the actual, real time process dynamics. This is in direct contrast to other "self-tuning" controllers that establish the values of tuning parameters based on an arbitrary process model.
While continuously scanning the process variables, EXACT control initiates corrective action upon sensing a process upset. The user selects the desired response by specifying the desired damping and overshoot-to-load change, such as quarter amplitude damping.
Values of EXACT can be read by the user.
EXACT control functions as if your best operator is on the job 24 hours a day. It can be turned on or off at the keypad or by configuring logic functions, allowing these controllers to function as advanced PID controllers.
EXACT control is available on both control loops.

## 3-VARIABLE INDICATOR

Up to two 3-variable indicator faceplates are available. Each variable has its own bargraph, digital engineering units, and loop tag. The 3 -variable faceplates are mutually exclusive with controllers and auto/manual stations. If only one controller or manual station is configured, one 3 -variable faceplate will be available.

## AUTO/MANUAL TRANSFER STATION

Up to two auto/manual stations are available. Auto/manual stations are mutually exclusive with controllers and indicators. For example, if only one indicator or manual station is configured, one auto/manual station will be available.

## PULSE DRIVEN INPUT

There is provision for two pulse inputs, forming a pulse up/pulse down pair that can be assigned to any scaled signal such as remote set point. This function is compatible with the signals used for older stepping motor type devices.

## RS-485 SERIAL COMMUNICATIONS INTERFACE

This controller is equipped with an RS-485 serial port for communication with most host computers, either directly or via an RS-232/RS-485 converter or equivalent accessory. Protocol conforms to ANSI Specification X3.28-1976, Subcategory E3. Using the Foxboro Model F6501A converter, up to 90 controllers can be accommodated with a single host communication port.
Serial communications capability includes uploading/downloading of configuration, setting of Auto/Manual (A/M) or Remote/Local (R/L) status and manual output and local setpoint values, polling of all inputs, outputs, and totalizers, and writing as well as reading of all configurable parameters. Both control loops are accommodated. The user can also select parity, and panel, workstation (host), or "both" priority.

## COMPUTATIONAL CAPABILITY

This controller performs up to three independent calculations. The variables may include the results of other calculation blocks, scaled and conditioned inputs, and other internal control signals.
An equation is entered from the keypad one character at a time following the usual rules of algebra and a few easy-to-learn rules. The result of this flexibility is exceptional computational capability in a single station controller.

## SIMPLIFIED CONFIGURATION AND OPERATION

Because of its flexibility, this controller is easily configured to meet the most exacting process requirements. All operating functions are examined and/or changed by keystrokes. Interactive prompting simplifies setting the adjustable parameters.

## COMPLETE SECURITY

The operator has keypad access to read the values of inputs, alarm and limit settings, and the operating configuration. However, the operator can adjust only those settings which were specified as operatoradjustable when the controller was configured. A passcode must be entered from the keypad to enable adjustment of the remaining parameters. In addition, a keypad disable jumper, accessible from inside the tamper resistant enclosure, is provided.
This passcode is determined by an authorized person at the time the controller is configured. Thus, only those who have been given this passcode can change any of the protected parameters.

## BOOLEAN LOGIC CAPABILITY

There are five single gates and five dual gates. Each gate is configured by selecting the logic and then selecting the source of each input. Gates 0 through 4 are the single input gates and are configured DIRECT or NOT by the user. Gates 5 through 9 are the dual input gates and the user selects one of the following logic types for each one: OR, NOR, AND, NAND, XOR, or XNOR.

## DYNAMIC COMPENSATION

The result of a dedicated calculation block can be passed through a dynamic compensator, prior to distribution. The dynamic compensator provides lead/lag, impulse, and dead time functions, each with its individual follow (bypass) switch. Functionally, dead time precedes lead/lag and is the input to the lead/lag function.
Utilizing the dynamic compensator and the follow switches, feedforward and other complex control applications are easily and efficiently handled.

## FRONT PANEL

The controller can be configured and operated entirely from the front panel without need for any external equipment. The panel consists of an alphanumeric display, a graphics display, status indicators, an alarm indicator (horn symbol), and a keypad. Refer to Figure 1.
The alphanumeric display at the top of the front panel has two lines of nine characters each. The characters are $5 \mathrm{~mm}(0.196 \mathrm{in})$ high, and colored Blue-Green.
The graphics display consists of three bargraghs, each having 50 segments plus a pointer on top and
bottom. The bars are 55.4 mm (2.18 in) long. The left and center bargraphs are 5 mm ( 0.196 in ) wide, and the right bar graph is narrower at 2.5 mm ( 0.098 in ). The bargraphs are colored Blue-Green.
The status characters (W/P, R/L, A/M) are 4 mm ( 0.157 in ) high; the alarm symbol is 5 mm ( 0.196 in ) high. The status characters are colored Blue-Green; the alarm symbol is Red.
The keypad has eight keys as shown in Figure 1 and identified in Table 1 on Page 5. The key switches are single pole, normally open contacts, all closing to a common lead.


Figure 1. Controller Front Panel

## COPY MEMORY FEATURE

This optional copy memory feature permits the configuration of one controller to be duplicated for use in another controller. This is accomplished using two NOVRAMs (nonvolatile, random access memory modules) and a configuration copy accessory. Briefly, after turning off the power, the procedure is as follows: remove the configured NOVRAM from the controller; install the copy accessory; plug the
configured NOVRAM and a second NOVRAM (to be configured) into the copy accessory; then turn on the power and the second NOVRAM is copied for use in another controller. With minimum effort, any number of controllers can thus be configured with the same parameter values as the original controller. Then individual parameters in each controller are easily changed to fit the particular loop.

## Table 1. Keypad Description

| Key <br> Name | $\quad$ Usage of Key |
| :---: | :--- |$|$| Depression when the Controller is in the PANEL (P) mode, causes the Controller to exit from the |
| :--- | :--- |
| operator FACEPLATE and enter the READ or SET menu. When the Controller is in the |
| WORKSTATION (W) mode, the TAG is disabled. |

OPERATING AND STORAGE CONDITIONS

| Influence | Reference Operating <br> Conditions | Normal Operating <br> Condition Limits | Operative Limits | Transportation and <br> Storage Limits |
| :--- | :---: | :---: | :---: | :---: |
| Ambient <br> Temperature | $23 \pm 2^{\circ} \mathrm{C}$ <br> $\left(73 \pm 3^{\circ} \mathrm{F}\right)$ | -10 and $+60^{\circ} \mathrm{C}$ <br> $\left(14\right.$ and $\left.140^{\circ} \mathrm{F}\right)$ | -10 and $+60^{\circ} \mathrm{C}(\mathrm{a})$ <br> $\left(14\right.$ and $\left.140^{\circ} \mathrm{F}\right)(\mathrm{a})$ | -40 and $+70^{\circ} \mathrm{C}$ <br> $\left(-40\right.$ and $\left.+158^{\circ} \mathrm{F}\right)$ |
| Relative <br> Humidity | $50 \pm 10 \%$ | 5 and $95 \%$ | 5 and $95 \%$ | 0 and $100 \%$ |
| Supply <br> Voltage | $24,120,220$ and <br> $240 \mathrm{~V} \mathrm{ac}, \pm 1 \%$ <br> $24 \mathrm{~V} \mathrm{dc}, \pm 1 \%$ | $\mathrm{V} \mathrm{ac},+10,-15 \%$ <br> $\mathrm{~V} \mathrm{dc},+10,-15 \%$ | $\mathrm{V} \mathrm{ac},+15,-20 \%$ <br> $\mathrm{~V} \mathrm{dc},+10,-15 \%$ | - |
| Supply <br> Frequency | $50 / 60 \mathrm{~Hz}, \pm 0.1 \mathrm{~Hz}$ | $50 / 60 \mathrm{~Hz}, \pm 3 \mathrm{~Hz}$ | 40 and 65 Hz | - |
| Vibration | Negligible | 5 and 500 Hz <br> at an acceleration <br> of $10 \mathrm{~m} / \mathrm{s}^{2}(1$ " g ") | - | $10 \mathrm{~m} / \mathrm{s}^{2}(1$ " g ") <br> for 1 hour when in <br> shipping container |
| Mechanical <br> Shock | Negligible | - | - | A 36 inch drop when <br> in shipping container. |

(a) Lower operative limit extends to $-20^{\circ} \mathrm{C}\left(-4^{\circ} \mathrm{F}\right)$ with enclosure heater option.

## PERFORMANCE SPECIFICATIONS

## Accuracy at Numeric Display

See the table below.
Numeric Display Accuracy Table

| Parameter | Accuracy |
| :--- | :--- |
| Set Point | $\pm 0.1 \%$ of span |
| Input | $\pm 0.1 \%$ of span |
| Analog | $\pm 0.5^{\circ} \mathrm{C}$ |
| RTD (Direct Meas.) | $\pm 0.5 \%$ of span |
| Output | $\pm 0.5^{\circ} \mathrm{C}$, reading only |
| Linearization | $\pm 0.5^{\circ} \mathrm{C}$, reading only |

## Resolution

## DISPLAY

$\pm 0.1 \%$ of upper range value
BARGRAPH
$\pm 2 \%$ of upper range value

## Frequency Response

Analog input to output conversion is flat to 3 Hz .

## Output Noise

0.25\% maximum, peak-to-peak.

## Humidity Effect

Maximum error in any conversion, calculation, or setting is $\pm 0.1 \%$ of span for a change from reference conditions to $95 \%$ R.H. at $30^{\circ} \mathrm{C}\left(85^{\circ} \mathrm{F}\right)$ wet bulb.

## Ambient Temperature Effect

Maximum error in percent of span, except as noted, for a $30^{\circ} \mathrm{C}\left(55^{\circ} \mathrm{F}\right)$ change in temperature within normal operating limits. See table below.

| Parameter | Maximum Error |
| :--- | :--- |
| Set Point <br> Local <br> Remote | less than $0.1 \%$ <br> less than $0.5 \%$ |
| Input <br> Analog <br> Frequency <br> RTD | less than $0.5 \%$ <br> less than $0.25 \%$ |
| less than $0.5^{\circ} \mathrm{C}$ |  |

## Supply Voltage Effect

$\pm 0.1 \%$ of span (maximum) for a $+10 \%$ or $-15 \%$ change in ac or dc voltage within normal operating conditions.

## FUNCTIONAL SPECIFICATIONS

## Proportional Input Signals

Any combination of the following proportional inputs; not to exceed four analog ( $4-20 \mathrm{~mA}, 1-5 \mathrm{~V}$, TC, or RTD) and two frequency inputs. All input signals are converted ten times per second and can be characterized or combined in a variety of calculations. See table below.

| Proportional Type Input Signal | Maximum Number | Details |
| :---: | :---: | :---: |
| 4 to 20 mA dc Current Input | 4 | 4 to 20 mA dc input is standard. Inputs are across 250 O resistors located inside housing. |
| 1 to 5 V dc Voltage Input | 4 | Controllers will accept 1 to 5 V dc by removing the input resistor(s) used with the current input. |
| Thermocouple Input (requires 893 Temperature Transmitter, or equivalent) | 4 |  |
| 1 to 9999 Hz Frequency Input | 2 | Input pulse rates, voltage levels, and field power are compatible with Foxboro E83 Series Vortex Flowmeter, and with Foxboro 81 and 82 Series Turbine Flowmeter having a preamplifier input. Input impedance is 2500 . |
| 1 to 9999 Hz Pulse Up/ Pulse Down Inputs (Uses both Frequency Inputs.) | 1 Pair | 1 to 9999 Hz pulse up/pulse down pair of inputs driven by external contact closure or voltage pulse. Contact closure/open times and pulse voltage level are compatible with older stepping motor devices. |
| Resistance Temperature Detector (RTD) Input, Direct or Temperature Difference Measurement. See Model Code section to select this optional RTD input. | 1 | Platinum, per IEC 100 or SAMA* 100 (RC 21-4) temperature curves. Linearization of displayed value is provided, as follows: $\begin{array}{ccc}  & \text { IEC } 100 & \text { SAMA } 100 \\ \text { Range } & -200 \text { to }+850^{\circ} \mathrm{C} & -200 \text { to }+600^{\circ} \mathrm{C} \\ & \left(-330 \text { to }+1560^{\circ} \mathrm{F}\right) & \left(-330 \text { to }+1100^{\circ} \mathrm{F}\right) \\ \text { Span } 110 \text { to } 1000^{\circ} \mathrm{C} & 110 \text { to } 800^{\circ} \mathrm{C} \\ & \left(198 \text { to } 1800^{\circ} \mathrm{F}\right) & \left(198 \text { to } 1440^{\circ} \mathrm{F}\right) \end{array}$ |

*Scientific Apparatus Makers Association.

## Two Discrete Inputs

Two nonisolated contact or transistor switch inputs, 5 V dc nominal open circuit voltage, 1 mA maxi-mum current. For remote status changes such as $A / M$, R/L, W/P, EXT ACK, and tracking functions.

## Control Functions

Within this station are two independent controllers with individual built-in options that can be configured. This station is also user-configurable to function as a single controller, cascade controllers, or an auto selector.
For each controller, the standard algorithms are P, I, PD, PI, PID, and EXACT control. The following options may be configured: nonlinear extender, ratio, measurement and set point tracking, output tracking, remote/local set point, output multiplication or summing, external reset, external limits for output, and simple batch control.

## Output Signals

TWO NONISOLATED ANALOG OUTPUTS

- Output One: 4 to 20 mA nominal into $500 \Omega$ maximum; isolation provided as an option.
- Output Two: 4 to 20 mA nominal into $500 \Omega$ maximum, or 1 to 5 V dc nominal into $2 \mathrm{k} \Omega$ minimum, jumper selectable. Can be assigned by user for control, measurement, set point, or conditioned input signals.


## TWO DISCRETE OUTPUTS

Two nonisolated open collector transistor (NPN) switch outputs. For status indication of $A / M, R / L$, W/P, and alarms, or can be configured as the destination for any two of the Boolean Gate Inputs. Contact ratings are 50 V dc maximum, 250 mA maximum. Leakage current is $100 \mu \mathrm{~A}$ maximum.

## Other Control Functions

- Input bias, gain, and output bias available for every input.
- Characterizers (two available, 8 segments each, assignable).
- Boolean Gate Logic \{DIRECT and NOT (single input); OR, NOR, AND, NAND, XOR, and XNOR (dual input); 18 function switches. Inputs selectable from contact inputs, alarm output states, status indicator outputs, EXACT state, gate outputs, and three fixed states.\}
- Signal Conditioning (square, square root, characterizer).
- Split range outputs (configurable for both 4-20 mA outputs)


## Alarms

Four dual-level alarms, each with a dead band and one Boolean output are available. Each alarm is configurable for Absolute, Deviation, Rate-ofChange, High/Low, High/High, Low/Low, Latching, Nonlatching, or Permissive. Each alarm can be configured to act on any one of a number of userselected points.

- Can be configured to indicate alarm status by a combination of alphanumeric display, the bar graphs, an alarm symbol, and the contact outputs.
- The alarm dead band is adjustable between 0 and $100 \%$ of span.


## Calculations

There are three calculation functions, designated CALC 1, CALC 2, and CALC 3. The variables in each calculation can be any combination of direct inputs to the controller, configured constants, and results of other calculation blocks. The available operators are $+,-, /,{ }^{*},>,<, \div, \sqrt{ }$ and ten Boolean gates. Open and close brackets are also available for grouping variables.

## Transmitter Power Supply

Nominal 28 V dc power supply with a $250 \Omega$ limiting resistor at each transmitter connection. Provides field power for two 4 to 20 mA transmitters with a maximum series resistance of $350 \Omega$ in each current loop, including the $250 \Omega$ input resistor.

## Execution Rate

Ten times per second.

## Toggle Mode

Configuring the TOGGLE mode allows a user to toggle (switch) between a menu level and the normal front panel display with a single keystroke.

## Dynamic Compensation

The result of CALC 3 may be passed through the dynamic compensator function prior to distribution. This block provides lead/lag, impulse, and dead time functions, each with its individual follow switch. Functionally, dead time precedes lead/lag and is the input to the lead/lag function.
Dead time allows the input to CALC 3 to be delayed by a configured time before making it available to the output of CALC 3. The lead/lag function allows the output to dynamically lead or lag the input by a configured time. Both functions can be enabled or by-passed selectively utilizing the follow switches. The impulse can be positive, negative, or bi-polar and is part of the lead/lag function.

## Dynamic Compensation Adjustment Limits

 DEAD TIME 0 and 200 minutesLEAD/LAG TIME 0 and 200 minutes

## Memory

All configuration and operating parameters (not status data) are stored in a nonvolatile RAM device having a ten year data retention capability. Should a power failure occur, essential control settings and last operating conditions are saved indefinitely. No batteries are used.

## Input Filter

Second order Butterworth filter. Adjustable from 0 to 10 minutes in 0.01 minute intervals.

## Signal Distribution

Over thirty signals are available for internal routing. These are the conditioned and scaled inputs, unconditioned inputs, control inputs and outputs, and calculation results.

## Power Consumption

15 VA maximum with 4 to 20 mA output; 27 VA
maximum with optional enclosure heater
Power On/Off Switch
A rocker type ON/OFF power switch is provided within the enclosure.

## PHYSICAL SPECIFICATIONS

## Enclosure

The case is a glass fiber reinforced polyester molding, compounded for superior corrosion resistance. The door is glass fiber reinforced, modified polyphenylene oxide. The overall construction meets IEC IP66, and provides the environmental and corrosion resistant protection of NEMA Type 4X.

## Electrical Connections

Electrical conduit holes, located on bottom of enclosure, accommodate $1 / 2$-in conduit (see "Dimensions - Nominal" section). User signal wires, with a maximum size of \#14 AWG ( $2.50 \mathrm{~mm}^{2}$ ), are terminated at a 32 -terminal block at the lower rear surface of the case. Power wires, ranging in size from \#22 to \#12 AWG ( 0.5 to $4 \mathrm{~mm}^{2}$ ), terminate at a 3 -terminal block (having a protective cover) at the bottom of the case.

## Keypad

The sealed contacts are stainless steel snap domes trapped between an upper and lower silver contact. Overlay colors are Red for ACK; Blue for $\uparrow$, $\downarrow$, and SEL; Light Gray for W/P, R/L, and A/M; Gray for TAG; and Black for background.

## Display

Vacuum fluorescent lamps in glass enclosure having a glass frit seal and tin plated copper pin outs. Horn symbol (for alarms) is Red, and bargraphs and alphanumeric characters are Blue/Green.

## Electronic Packaging

The electronic circuitry is mounted on two 1.6 mm ( 0.062 in) thick, glass-based epoxy, wiring boards. These electronic printed wiring assemblies (PWA's) are interconnected using 20 -pin connectors.

## Mounting

Enclosure can be mounted to a panel, to a flat surface, or to a DN50 or 2 in pipe. For enclosure and mounting dimensions, see "Dimensions-Nominal" section.

## Approximate Mass

6.4 kg ( 14 lb )

## PRODUCT SAFETY SPECIFICATIONS

## Electrical Classification (See Note Below)

| Testing Laboratory, Types of <br> Protection, and Area Classification | Conditions of Certification | Electrical Certification <br> Specification |
| :--- | :--- | :---: |
| CSA: Certified for use in ordinary (non- <br> hazardous) locations. | - | CS-E/CGZ |
| CSA: Suitable for Class I, Groups A, B, <br> C, and D, Division 2 hazardous <br> locations. | Without Enclosure Heater: <br> Temperature Code T4. <br> With Enclosure Heater, Optional <br> Code "-3": Temperature Code T3. | CS-E/CNZ |
| FM: Nonincendive for Class I, Groups <br> A, B, C, and D, Division 2 hazardous <br> locations. | Not available with enclosure heater, <br> Optional Code "-3". Temperature <br> Code T4. | CS-E/FNZ |

NOTE
These Controllers have been designed to meet the electrical classifications listed in the table above.
For detailed information or status of the Agency approvals, contact Foxboro.

MODEL CODE

| Description | Model |
| :--- | :---: |
| Enhanced FIELD STATION MICRO Controller | 743 CB |
| Nominal Supply Voltage and Frequency | -A |
| $120 \mathrm{~V} \mathrm{ac,50/60Hz}$ | -B |
| $220 \mathrm{~V} \mathrm{ac}, 50 / 60 \mathrm{~Hz}$ | -C |
| $240 \mathrm{~V} \mathrm{ac}, 50 / 60 \mathrm{~Hz}$ | -D |
| 24 V dc | -E |
| $24 \mathrm{~V} \mathrm{ac}, 50 / 60 \mathrm{~Hz}$ | -J |
| 100 V ac, $50 / 60 \mathrm{~Hz}$ | F |
| Mounting | P |
| Pipe Mounting | -1 |
| Panel or Surface Mounting | -1 |
| Optional Selections | -2 |
| Output Isolation, 4 to 20 mA (Output 1 only) | -3 |
| Platinum RTD Input(a) (Input 1 only) |  |
| Enclosure Heater (Not Available with $743 \mathrm{CB}-\mathrm{D}, 24 \mathrm{~V}$ dc Supply) Required for Operating |  |
| Temperature below $-10^{\circ} \mathrm{C}\left(+14^{\circ} \mathrm{F}\right)$ down to a lower limit of $-20^{\circ} \mathrm{C}\left(-4^{\circ} \mathrm{F}\right)$ |  |
| Examples: $743 \mathrm{CB}-\mathrm{AP}, 743 \mathrm{CB}-\mathrm{BF}-2,743 \mathrm{CB}-\mathrm{AF}-123$ |  |

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## OPTIONAL FEATURES AND ACCESSORIES

## Output Isolation

This option provides an isolated 4 to 20 mA nominal signal ( $500 \Omega$ load maximum) on output number 1. Select Model Code Optional Suffix " -1 ".

## Platinum RTD Input

This option provides for accepting a platinum RTD on input number 1. Calibrated per IEC 100 or SAMA 100 temperature curves. Each curve is linearized for digital readout over the ranges and spans listed below:

IEC 100 (Direct or $\Delta T$ Measurement)
Range: -200 to $+805^{\circ} \mathrm{C}\left(-330\right.$ to $\left.+1560^{\circ} \mathrm{F}\right)$
Span: 110 to $1000^{\circ} \mathrm{C}\left(198\right.$ to $\left.1800^{\circ} \mathrm{F}\right)$
SAMA 100 (Direct or $\Delta$ T Measurement)
Range: -200 to $+600^{\circ} \mathrm{C}\left(-330\right.$ to $\left.+1100^{\circ} \mathrm{F}\right)$
Span: 110 to $800^{\circ} \mathrm{C}\left(198\right.$ to $\left.1440^{\circ} \mathrm{F}\right)$
Specify by selecting Model Code Optional Suffix "-2".

## Configuration Copy Accessory

All of the operating configuration is stored in a NOVRAM. The copy accessory permits the entire contents of the memory module to be quickly copied to another NOVRAM, either a spare or one from another controller. Specify Part Number L0122TU for the copy accessory, and Part Number L0122RJ for a spare NOVRAM.

## Enclosure Heater

A thermostatically controlled enclosure heater option is required when operating at ambient temperatures below $-10^{\circ} \mathrm{C}\left(+14^{\circ} \mathrm{F}\right)$. By using the heater, operation of the controller is extended down to $-20^{\circ} \mathrm{C}\left(-4^{\circ} \mathrm{F}\right)$. This heater is not available with the 24 V dc supply (743CB-D). Specify by selecting Model Code Optional Suffix "-3".

## Surge Suppressor

A surge suppressor is optionally available for use with serial communication input when external wiring is located near transient producing sources such as meters, solenoids, high voltages, etc. Specify Auxiliary Specification (AS) SURSUP.

## Factory Pre-Configuration

Unless otherwise specified, the controller is shipped with a Factory Default configuration consisting of a single measurement input, a local set point, PID EXACT control with EXACT turned off, and scale ranges of 0 to 100 percent.
Optional Factory Configurations are shown in Table 2. Because the controller is so powerful and virtually offers an unlimited number of solutions, only some of the more common basic applications are listed. Select the configuration that most closely meets your needs. Any changes necessary to meet your specific needs can easily be made in the field. It usually will be necessary to change, at minimum, the loop tag, the scale ranges, and the PID controller turning parameters to suit process requirements. Optional factory pre-configuration is offered without additional charge. To order, refer to Table 2 and specify the Auxiliary Specification (AS) for the configuration that most nearly meets your needs. The AS will be displayed in the loop tag to assist in initial field identification.

Table 2. Factory Pre-Configuration Options

| Description | AS(a) <br> Reference |
| :---: | :---: |
| Single Loop Controller with Hi/Lo Measurement Alarm with One Totalizer with Hi/Lo Alarm and Totalizer with Split Range Outputs with 3-Variable Indicator Station with Auto/Manual Transfer Station | SINGL C <br> SINGL C1 <br> SINGL C2 <br> SINGL C3 <br> SINGL C4 <br> SINGL C5 <br> SINGL C6 |
| Dual Loop Controller with Hi/Low Measurement Alarms with two Totalizers with Alarms and Totalizers | DUAL C <br> DUAL C1 <br> DUAL C2 <br> DUAL C3 |
| 3-Variable Indicator Station <br> with three Hi/Lo Alarms <br> with two Totalizers <br> with Alarms and Totalizers <br> with second 3 -Variable Indicator Station <br> with second 3-Variable Indicator Station, Hi/Low Alarms and Totalizers with Auto/Manual Transfer Station | IND S <br> IND S1 <br> IND S2 <br> IND S3 <br> IND S4 <br> IND S5 <br> IND S6 |
| Auto/Manual Transfer Station <br> with Hi/Low Alarm <br> with Totalizer <br> with Alarm and Totalizer <br> with second Auto/Manual Transfer Station <br> with second Auto/Manual Transfer Station, Hi/Low Alarms and Totalizers with Split Range Outputs | A/M S <br> A/M S1 <br> A/M S2 <br> A/M S3 <br> A/M S4 <br> A/M S5 <br> A/M S6 |
| Single Loop Flow Ratio Controller, 0 to 2 Ratio Range, Square Root Inputs with Hi/Low Alarm <br> with one Totalizer with Hi/Low Alarm and Totalizer with Split Range Outputs with 3-Variable Indicator Station with Auto/Manual Transfer Station | RATIO C RATIO C1 RATIO C2 RATIO C3 RATIO C4 RATIO C5 RATIO C6 |
| Cascade Controller with Hi/Low Primary Alarm with one Totalizer with Hi/Low Alarm and Totalizer | CASCDE C CASCDE C1 <br> CASCDE C2 <br> CASCDE C3 |
| Auto Selector Controller, Low Select with Hi/Low Alarms with Totalizer with Alarms and Totalizer with High Select | A SEL C <br> A SEL C1 <br> A SEL C2 <br> A SEL C3 <br> A SEL C4 |
| Single Loop Controller with Pulse- or contact-driven Set Point | PULSE SP |
| Single Loop Controller with Output Freeze from External Contact Input 1 | FREEZE |
| Single Loop Controller with Output Switching to a Preset Value from External Contact input 1 | PRESET |

(a)Auxiliary Specification

## ORDERING INSTRUCTIONS

1. Model Number
2. Electrical Classification
3. Optional Features
4. Accessories
5. Optional Factory Pre-Configuration
6. User Tag Data

## DIMENSIONS - NOMINAL

$\frac{\mathrm{mm}}{\mathrm{in}}$


SIGNAL
A 32-TERMINAL BLOCK MAXIMUM WIRE SIZE IS \#14 AWG ( $2.5 \mathrm{~mm}^{2}$ )

POWER
A 3-TERMINAL BLOCK, WIRE SIZE RANGE IS \#22 TO \#12 AWG ( 0.50 TO $4.0 \mathrm{~mm}^{2}$ )

POWER, $1 / 2 \mathrm{in}$, CONDUIT

$1 / O, 1 / 2$ in CONDUIT

OTHER I/O, $1 / 2$ in CONDUIT (KNOCKOUTS TO BE USED AS REQUIRED)

BOTTOM VIEW


PIPE MOUNTING


NOTES:

1. FOR HORIZONTAL MULTIPLE PANEL MOUNTING, A MINIMUM DISTANCE OF 267 mm ( 10.5 in ) FROM CENTER LINE TO CENTER LINE IS REQUIRED.
2. FOR VERTICAL MULTIPLE PANEL MOUNTING, A MINIMUM DISTANCE OF 376 mm ( 14.8 in ) FROM CENTER LINE TO CENTER LINE IS REQUIRED.

## PATENT NOTICE

This product and its components are protected by one or more of the following U.S. Patents, and other patents pending: 4, 616, 332; 4, 658, 348; 4, 704, 676; RE 33267; and corresponding foreign patents.

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[^0]:    ${ }^{(a)}$ Minimum span with platinum RTD input is $110^{\circ} \mathrm{C}\left(198^{\circ} \mathrm{F}\right)$.

